Design and Analysis of Distance Sampling Studies

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Part 3 - Conventional Distance Sampling - Survey Design

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Survey Design

Do you need distance sampling?

- Not all animals can be detected in traditional strips or quadrats?
- No information needed on population parameters such as survival rates?
- Density is sensible but population abundance is ill defined.

Line vs. point sampling

- Line transect sampling uses all detection along route. In point transect, detections during travel between points is ignored.
- Line transect better at capturing animals close to line; in point transect, area searched close to point is small.
- Point transects good for fragmented habitats.
- Point transects good for multi-species (bird) surveys.

Standard considerations

- What are your objectives? Density estimation?
- What is geographic range/scope of estimate?
- What subdomains do you need (e.g. density by sex? Density by habitat type?)
- Sampling time relative to animal movement.

Good results require RRRs in survey design:

- Randomization makes the survey representative
 - Avoid subjective placement.
 - Systematic placement likely good a random placement (self randomization assumed) as long as systematic placement does not match feature in study area.
 - Run systematic transects perpendicular to known gradient in density.
 - All areas of study area should have equal probability of selection (at least within strata)
- Replication gives you adequate precision
 - Multiple short lines better than few longer lines.
 - 15+ replicate lines needed to get estimate of encounter rate variation.
- Stratification control for KNOWN noise.
 - Avoid too many strata (2 or 3 are usually sufficient).
 - Post-stratification is ok, but you may not have all information needed to rollup.

Good results require attention to key assumptions

- g(0) = 1, i.e. animals detected on line/at point with certainty.
- Broad shoulder in detection function near 0.
- No movement of animals.
- Distance is determined accurately.
- Cluster size determined accurately.

$$\begin{split} \widehat{D}_{Line} &= \frac{n\widehat{f(0)}\widehat{E[S]}}{2L} \quad \widehat{D}_{Point} = \frac{nf'(0)\widehat{E[s]}}{2\pi k} \\ \widehat{var}(\widehat{D_{Line}}) &= \widehat{D}^2 \times \left\{ \frac{\widehat{var}(n)}{n^2} + \frac{\widehat{var}(\widehat{f(0)})}{[\widehat{f(0)}]^2} + \frac{\widehat{var}(\widehat{E[s]})}{[\widehat{E[s]}]^2} \right\} \\ \widehat{var}(\widehat{D_{Point}}) &= \widehat{D}^2 \times \left\{ \frac{\widehat{var}(n)}{n^2} + \frac{\widehat{var}(\widehat{f'(0)})}{[\widehat{f'(0)}]^2} + \frac{\widehat{var}(\widehat{E[s]})}{[\widehat{E[s]}]^2} \right\} \end{split}$$

- Variation in n (the encounter rate) is out of control of the experimenter but might be improved by stratification into high and low density areas. Aim for 15+ points/lines. Avoid pseudo-replication by sub-dividing lines.
- Variation in f(0) and f'(0) depends on number of detections. Improves as $\sqrt{detection}$.
 - 50+ distances for each separate detection function fit in line transect;
 - 80+ for point transects (to account for area searched effect).
 - w should be set large relative to average observed distance.
 - Don't concentrate on object far away as they will likely be truncated.
- Variation in cluster size is out of control of experimenter. Try using as a covariate or as a stratification variable.

Absolute sample size is important and not relative sample size.

Two rough rules of thumb based on a pilot survey. Suppose that a target rse_t is desired (i.e. 95% ci is $\pm 2rse_t$)

$$L_{required} pprox rac{3}{[rse_t]^2} rac{L_{pilot}}{n_{pilot}}$$
 $L_{required} pprox rac{L_{pilot}[rse(\widehat{D}_{pilot})]^2}{[rse_t]^2}$

Argus example,

- We want $rse_t = 0.10$.
 - $L_{pilot} = 316$ km; n = 57
 - $rse(\widehat{D}_{pilot}) = 0.21$

$$L_{required} \approx \frac{3}{[.10]^2} \frac{316}{57} = 1700 \text{ km}$$

$$L_{required} \approx \frac{316[0.21]^2}{[0.10]^2} = 1400 \text{ km}$$

Same equation for point transect replacing L by k.

Two rough rules of thumb based on a pilot survey.

- Additional effort is needed if measuring clusters. See the Intro book for more details.
- Use the above even if you tend to stratify as a rough first guess. Allocate among strata roughly proportional to $A_h\sqrt{D_h}$.
- Precision essentially improves as \sqrt{effort} .

What to do if you have little preliminary information? A VERY, VERY, VERY, VERY rough LOWER bound for the effort needed is based on getting 100 distances based on a 50% average detectability on a strip half-width w when the density is D. Solve for L such that

$$100 = 0.5 \times 2Lw \times D$$

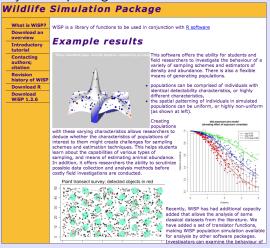
Argus example,

- $D \approx 0.025/\text{ha} = .0000025/\text{m}^2$
- $w \approx 100$ m.

This gives

$$L \approx \frac{100}{0.5 \times 2 \times 100 \text{ m} \times .0000025/\text{m}^2} = 800,000 \text{ m} = 400 \text{ km}$$

What to do if you have little preliminary information? Try WiSP package in R.



I have a simple script demonstrating how the package run in the WiSP Directory.

Distance sampling - Survey Design - Summary

- RRRs
- 15+ replicate lines; 40+ points
- 50+ distances for line transect; 80+ distances for point transect
- Do a pilot study to estimate how much effort will be needed in future.
- Use WiSP or other simulation features to estimate sample sizes in very difficult circumstances.